24 Power Supplies

Amateur radio equipment normally derives its power from one of four sources:

- The public AC mains which is nominally 230 volts at 50Hz in the EU, though 240 volts still exists in the UK.
- Batteries, which are either primary (non-rechargeable) or secondary (re-chargeable)
- Engine driven DC generators or alternators, whether separate or incorporated in a vehicle.
- Renewable sources such as wind, possibly water turbine or pedal driven generators, solar cells or rarely, thermocouples. As these are intermittent in nature, a secondary battery with a regulator must be used in conjunction.

For fixed stations the AC mains is readily available, is relatively cheap and is almost always used. It can be converted by transformers, rectifiers, smoothing circuits or switch mode (high frequency) circuits to a wide range of direct voltages and currents necessary for amateur equipment use.

Batteries, both primary and secondary (accumulators) have always provided a convenient though relatively expensive source of power, especially for low powered or portable rigs, or test equipment.

Discrete engine driven generators can give an output of DC or AC, but the most popular give an output of 240/230 V AC at a nominal 50Hz, matching the domestic mains. Car alternators at present provide charging for a 12V accumulator, though 42V may soon be common.

Renewable sources provide AC or DC according to type, and are discussed in detail later.

SAFETY

The operation of all power supplies (except perhaps low-voltage, low current primary batteries) can be dangerous if proper precautions are not taken. The domestic mains can be lethal. High voltage power supplies for valve equipment can also be lethal and great care must be taken with them. There is a case on record of 12 volts proving fatal, for it is not voltage which kills you but current, and the law of the late German doctor (Georg Siemon Ohm) applies. Having wet hands is asking for trouble; if you must handle high voltages, do so with one hand in your pocket.

Where petrol or liquefied gas is used for your engine's fuel, there is a fire hazard, particularly when re-fuelling. If you persist in re-fuelling while the engine is running, and have a fire, you will not get much sympathy from either your insurance company or relatives.

SUPPLIES FROM THE PUBLIC MAINS

It is assumed that the supply will be a nominal 230 volts at 50Hz in accordance with EU regulations.

A rectifier (or rectifiers) will be needed to convert AC to DC. Rectifiers are nearly always silicon PN junction or Schottky diodes but Silicon Carbide diodes will be met occasionally (see the chapter on semi-conductors for more on rectifier diodes).



Fig 24.1: Rectifier symbol



Fig 24.2: Rectifier circuits showing the output current waveforms with resistive loads. (a) half-wave, (b) full-wave or biphase half-wave, (c) bridge

These are all very efficient in that they have a very low forward voltage drop and a very high reverse resistance, within their rating. Copper oxide, selenium and germanium diodes are obsolete for this purpose. The diode has a conventional symbol (**Fig. 24.1**) in which the arrow points in the direction of current flow, not electron flow - so the arrow head is the anode, and the plate the cathode. By convention it is the cathode, which is marked +, banded or coloured red because it is positive when rectifying AC.

Fig. 24.2 shows three types of rectifier circuits which are widely used in amateur Power Supply Units (PSUs), together with waveforms of the current supplied by the rectifier(s). In all cases this can be resolved into a DC and an AC component. The latter is called ripple, and requires removal. It can be seen that the half-wave circuit of **Fig 24.2(a)** has a worse ripple than either of the full wave circuits, and has the lowest frequency component (50Hz). Also notice that DC flows through the transformer, which may cause saturation and over-heating if the transformer is not designed for this purpose. Consequently it is not much used.

The full-wave circuit of **Fig 24.2(b)** needs a centre-tapped transformer while the bridge circuit of **Fig 24.2(c)** does not. The bridge incurs two diode (voltage) drops but uses the transformer winding more efficiently. Microwave oven transformers are not designed to use bridge rectifiers, and the insulation (if any) of the low potential end is inadequate, but the circuit of Fig 24.2(a) may be used if the high leakage reactance of the transformer can be tolerated. The oven power supply cannot be used without modification, as it is neither smooth enough nor of the right polarity to feed a valve amplifier.

In most cases the rectifier diodes feed a large capacitor (the smoothing or reservoir capacitor), which stores energy during the part of the cycle when the diodes are not conducting. In a few cases the diodes feed an inductor (choke) which is then followed by a capacitor. The choke is heavy and expensive, but



Table 24.1: Operating conditions of single-phase rectifier circuits

Туре	VRRM	lav	IFRM	IFSM
Diodes				
1N4001*	50	1.0	10	20
1N4007*	1000	1.0	10	20
1N5401†	100	3.0	20	60
1N5408†	1000	3.0	20	60
BY98-300	300	10	50	100
BY98-1200	1200	10	50	100
BY96-300	300	30	100	200
BY96-1200	1200	30	100	200
Bridge rectifiers				
1KAB10E	100	1.2	25	50
1KAB100E	1000	1.2	25	50
MB151	100	15	150	300
MB156	600	15	150	300
GBPC3502	200	35	200	400
GBPC3506	600	35	200	400

Note: The diodes marked * and † are wire ended - the rest are mounted on screwed studs. V_{RRM} is the maximum reverse voltage or peak inverse voltage, lav is the average output current in amps, I_{FRM} is the maximum repetitive peak current in amps, I_{FSM} is the maximum non-repetitive peak forward current with a maximum duration of 5ms.

 Table 24.2: Electrical characteristics of some common diodes and bridge rectifiers

does lower the peak current in both diodes and capacitor.

A rectifier diode for mains frequency has three important parameters:

- Maximum mean forward current
- Maximum peak forward current
- The peak inverse voltage, which is encountered by the diode when it is not conducting. This is made up of the instantaneous voltage of the transformer, ie when it is at its negative peak, added to the voltage of the smoothing capacitor. Placing diodes in series is a means of increasing peak inverse voltage, but shunt resistors may be needed to ensure correct voltage distribution



Fig 24.3: Voltage multiplier circuits. (a) Half-wave voltage doubler; (b) full-wave voltage doubler; (c) voltage tripler; (d) voltage quadrupler. V^{-} = peak value of the AC input voltage. The working voltages of the capacitors should not be less than the values shown



Fig 24.4: Bridge rectifier with capacitor input filter

Table 24.1 shows the voltages and currents associated with various configurations. Table 24.2 gives the parameters for some of the more common of the many diodes now available.

Other categories are fast recovery diodes which are used along with Schottky (low forward voltage and fast recovery time) diodes in switch mode power supplies and soft recovery diodes, which because they switch relatively slowly, cause less RF interference.

Avalanche diodes break down on over-voltage throughout the silicon chip and not a localised spot.

There are many packages of four diodes as a bridge, ready to mount on a heat-sink. These are relatively cheap, but watch the manufacturer's peak inverse voltage rating; does it apply to the individual diodes or to the bridge? Table 24.2 also lists some common bridge packages.

Voltage Multipliers

When a DC voltage greater than the peak of the available AC is needed, a voltage multiplier circuit can be used. These can give a large voltage multiplication, but with poor regulation (decrease of output voltage with increase of load current). The operation may be visualised roughly by thinking of the diodes as 'ratchets'. The mechanical ratchet passes motion in one direction only, and in the multiplier, each stage 'jacks up' the voltage on the following stage. **Fig 24.3** shows some of the possible circuits.

Smoothing Circuits

These are low pass filters which follow the rectifier diodes, and the behaviour of the circuit depends on the input element of the filter. This is usually a capacitor in mains frequency circuits and a choke in switch mode PSUs. There may be further components where a greater ripple reduction is needed (see later in this chapter).

Capacitor input

An example is the bridge rectifier of **Fig 24.4** in which R_s is the effective resistance of the transformer (resistance of the secondary, plus the turns ratio times the primary resistance).

Fig 24.5 shows voltage and current waveforms of the capacitor as it charges up during part of the cycle and discharges during the rest. The ratio of output voltage to peak input voltage depends on the size of the capacitor, the load and effective resistance in series with the rectifier. Fig 24.6 shows the relationship graphically being 2 π times the input frequency.

The charging and discharging of the reservoir capacitor constitutes the ripple current and all electrolytic capacitors have a maximum ripple current rating (see the chapter on passive components). Exceeding the maximum will overheat the capacitor and shorten its life. Ripple current is difficult to calculate, but can be measured by using a true RMS ammeter, or estimated at three times the DC rating of the PSU.

The Radio Communication Handbook



Fig 24.5: Curves illustrating the output voltage and current waveforms from a full-wave rectifier with capacitor input filter. The shaded portions in (a) represent periods during which the rectifier input voltage exceeds the voltage across the reservoir capacitor, causing charging current to flow into it from the rectifier







Fig 24.7: Relationship between diode RMS current and percentage R_S/R_L for values of ωCR_L greater than 10. (ω = 314 for 50Hz mains). The dotted line applies to half-wave rectifiers



Fig 24.8: Diode peak current as a ratio of diode DC current for values of CRL greater than 10. Note: in a bridge rectifier circuit, diode DC current is half the load current. The dotted line applies to half-wave rectifiers; in this case the diode DC current is equal to the load current

As the effective resistance of the transformer becomes a smaller and smaller fraction of the load resistance, R_L , the peak rectifier current increases (see **Figs 24.7 and 24.8**). With increasing C (Fig 24.4) the peak rectifier current increases and the ripple current decreases (**Fig 24.9**). The efficiency also decreases, meaning more transformer and diode heating. A simple idea to avoid destroying the diodes by excessive current, is to limit the maximum peak current by adding a series resistor to augment the R_s of Fig 24.4. The minimum value of R_s is given by

$$R_{s} = V/I_{FRM}$$
(1)

where V is the output voltage of the transformer and ${\rm I}_{\rm FRM}$ the maximum peak current for the diode.

Then calculate the effective resistance of the transformer as already explained. If it is more than the value calculated above,



Fig 24.9: Percentage ripple voltage (RMS) against values of $\omega CR_L (\omega = 2\pi f$ where f is the mains supply frequency)

no augmentation is necessary. If it is less, add a series resistor to make up the difference, bearing in mind the necessary power rating.

Soft starting

When first switched on, the capacitor's inrush current may be excessive and there are means of limiting it.

A simple way is to connect an NTC thermistor (see the chapter on passive components) of correct current rating in series with the primary of the transformer, as in **Fig 24.10(a)**. Another way is to have a resistor in series with the primary, which is shorted by a relay whose coil is in parallel with the reservoir capacitor (**Fig 24.10(b**)).

This relay must be chosen so that it closes at about 75% of the normal output voltage. By putting the limiter in the primary, the doubling of the magnetising current and possible magnetic saturation when the transformer is switched on at a zero



Fig 24.10: Soft starting circuits. C1 is the smoothing capacitor. (a) Using R1, an NTC thermistor. (b) Using a relay to short out a series resistor. (c) A more sophisticated circuit. When power is applied, C1 charges up slowly because R1 and the low thermistor limit the inrush current. When C1 is sufficiently charged to operate RLA, the relay closes and RLA1 puts full mains voltage across the transformer primary. The high resistance part of the thermistor remains hot and keeps the 'low' part high. The circuit also provides over-voltage protection by 'crow-barring' C1 through the 2R2 resistor. An enhancement is to place a neon lamp in series with a 150 Ω resistor across the relay contact; this flashes briefly at switch-on and stays on if overvoltage occurs or an attempt is made to switch on with a load connected. [Fig 24.10(c) is reproduced by permisson from *Practical Wireless*]

crossing of the mains, is avoided.

A refinement of this circuit is shown in **Fig 24.10(c)**, where over-voltage protection is also provided.

Inductor (choke) input

Here the situation is different (see **Fig 24.11**) - if the inductor's value is above a certain limit (see below), current flows during the whole time (**Fig 24.12**), much reducing the peak value The critical value, (L_c) for the inductance in a full wave circuit is:

$$L_{c} = \frac{R_{S} + R_{L}}{6\pi f}$$
(2)

Where $L_{\rm c}$ is in Henrys, f is the supply frequency in Hertz, and resistances are in ohms. If $R_{\rm S}$ is much less than $R_{\rm L}$ and the frequency of the supply is 50Hz, for a full wave rectifier, this reduces to:

$$L_{c} = \frac{R_{L}}{940}$$
(3)

It will be seen that the inductance required increases as the load current decreases, (the load resistance R_L increases), so it may be necessary to provide a minimum current by means of a bleeder resistor if the inductor input is to remain effective (the output voltage will rise if it is not).

The value of this resistor in ohms is 940 times the maximum value of the inductor in henrys. The inductance of an iron cored coil depends on the current through it.



Fig 24.11: Bridge rectifier with choke input filter



Fig 24.12: Waveforms at rectifier output (point X in Fig 24.11) in a choke input circuit. (a) Voltage waveform. (b) Current waveform (L = L_c)



Fig 24.13: Circuit of a power supply for 13.8V at 5A

Choice of Components

The ideas given here are for power supplies which will always work but which may not be the most economical in components. The reason for this is that generally components are cheap, but time is important and troubleshooting can be difficult. Components should always be chosen on a 'worst case' basis. That is assuming that:

- The mains voltage can fluctuate from its nominal value by ±10%. This does not allow for drastic load shedding during a very hard winter!
- Electrolytic capacitors generally have a tolerance of +50% to -20%, so that a capacitor marked 100µF can have any value between 150µF and 80µF
- Rectifier diodes should have a peak inverse voltage rating of at least three times the output voltage of the transformer (if one is used), when the mains voltage is 10% higher than nominal. This does not allow for spikes on the mains, and either an even higher rating should be adopted or some means of spike reduction installed.
- Choose a diode or diodes with an average current rating of at least twice the required value.

Capacitor input

The secondary resistance of the transformer is assumed to be 0.1Ω and the primary resistance 5Ω . The turns ratio (see below) is 0.0729 to 1 so the effective resistance of (h

Fig 24.14: Additional smoothing sections to follow the circuits of Fig 24.4 or 24.11

30A and the RMS current from Fig 24.7 is 3.2 times the mean ie 8A.

- Assume ωCR_{L} = 100 (this is an arbitrary choice based on 5 the need for low ripple voltage - see later), so E_{DC}/E_{peak} = 0.95 (from Fig 24.6 which also shows that there is not much to be gained by increasing ωCR_L further). Therefore the secondary voltage = 13.8/0.95 = 14.5. However this does not include the voltage drop in each diode of about 1.5V (a total of 3V) so the secondary voltage required is 17.5V.
- 6 R_{L} is 2.76 so C is $100/(2\pi 50 \times 2.76)$ which equals 115,000µF, the mains frequency being 50Hz. Electrolytics have a tolerance of -20 to +50% so this would be scaled up to 150,000µF, an available value if somewhat expensive. Because of this, a higher voltage is often rectified, a smaller capacitor used, and the ripple removed by a voltage regulator circuit - see below.
 - Fig 24.9 gives the ripple as about 0.6%.

7

The input and output leads to the capacitor should have as little in common as possible to avoid the introduction of ripple. Take them independently to the capacitor terminals as shown in Fig 24.13.

The design of all other power supplies working from the mains, no matter what voltage or current, follows the same rules except the following:

- When an input inductor (choke) is used (see below).
- Where a 12 or 24V secondary battery (usually a vehicle battery) is 'floated' across a DC supply and takes the place of the reservoir capacitor.

the primary transferred to the secondary will be 0.027Ω and the total effective resistance of the transformer is 0.127Ω .

- 2 The bridge rectifier is a type SKB25/02, which is rated at an average current of 10A, a peak current of 359A and peak inverse voltage of 200V. The RMS transformer output voltage is 17.7V (see below). The minimum value of R_s is $17.7/350 = 0.047\Omega$, which is well below the effective resistance of the transformer, so no added resistance will be necessarv.
- 3 $R_s/R_L = 0.047 / 2.76 = 0.017$ or 1.7%. The average diode current is 2.5A (two diodes share the 5A).
- Δ Referring to Fig 24.8, the peak

10.0 eı e2 С e2 e1 (2TTf)2 LC-1 <u>ele</u> Ripple 1.0 % Ŷ, 0. ic 100 200 300 500 700 1000 L (Henries) x C (Microfarads) 2000 3000 5000 20 30 50 70

diode current is 12 times this ie Fig 24.15: Relationship between large ripple and product of LC





Inductor (Choke) input

Here the inductor is connected directly to the rectifier diodes (Fig 24.11) and is followed by a smoothing capacitor. Note that it is equally possible to use a centre-tapped transformer and just two diodes to make a full wave rectifier.

As mentioned above in equations (2) and (3), the inductor must have a certain minimum value for a given load. This must be calculated for the smallest current expected, which may only be that of a bleeder, if fitted.

The voltage and current values and waveforms for a circuit using at least this value of inductance are shown in Fig 24.12. It is clear that the peak rectifier current is only double the mean current. Under these conditions the transformer RMS current is 1.22 times the load current and the average current per diode is half the load current.

The output voltage is 0.9 of the transformer RMS output minus voltage drops in winding resistance of both transformer and choke less the diode(s) drop. The diode drop can be neglected for power supplies above say 100V and estimated from manufacturer's data where significant. (Power diodes do not just drop 0.6V!)

The value of the filter capacitor (the first if more than one) is arranged to give the wanted ripple voltage ER from the equation:

$$ER = \frac{\text{output voltage}}{0.8LC}$$
(4)

where L is in henrys, C in microfarads and the supply frequency 50Hz (full wave rectification).



Fig 24.17: Circuit of a dualvoltage power supply Further smoothing can be added to either capacitor or inductor input by means of LC or RC circuits as in **Figs 24.14, 24.15 and 24.16**. The RC circuit is unsuitable for high currents because it drops the voltage.

Care must be taken that L and C do not resonate at the ripple frequency or any harmonics thereof. For a full wave circuit on 50Hz, the lowest ripple component is at 100Hz and the LC product is 2.53 for resonance. Normally LC is very much higher than this (see Figs 24.15 and 24.16). Note that the choke should be designed so that it does not become magnetically saturated at full DC output. An air gap in the core will help in this respect. The 'swinging choke' is so designed that it does approach saturation at full output and has a higher inductance at low currents where it is needed to satisfy equation (3).

Dual Power Supply

The circuit of **Fig 24.17** shows a dual voltage supply from a centre-tapped transformer. On analysis, although it uses a bridge rectifier, the two halves of the bridge feed the two supplies separately. The earth point may be chosen to give V and V/2 or +V and -V as required.

Voltage Regulators or Stabilisers

These are circuits that give a virtually constant voltage output regardless of load or input, within certain limits. They are necessary for supplying variable frequency oscillators (VFOs), DC amplifiers and some logic circuits. At higher voltages they are necessary for supplying screen and/or grid bias for valve amplifiers.

Shunt regulators - zener diodes

These are diodes with a sharp breakdown voltage, (see the chapter on semi-conductors). If fed from an un-regulated source through a resistor (**Fig 24.18**) it forms a simple regulator for more or less constant loads, with the advantage of being able to source or sink current.



being able to source or Fig 24.18: A simple zener diode voltsink current. age regulator

Туре	Zener voltage (V)	Normal operating current (A)	Zener slope resistance (Ω)	Maximum dissipation (W)	Temp coeff (mV/°C)
BZX79C2V4	2.4	0.005	100	0.4	3.5
BZX79C6V2	6.2	0.005	10	0.4	+2.0
BZX79C75	75	0.002	255	0.4	+80
BZT03C7V5	7.5	0.1	2	3.25	+2.2
BZT03C270	270	0.002	1000	3.25	+300
BZY91C10	10	5.0	NA	75*	NA
BZY91C75	75	0.5	NA	75*	NA

* On a heatsink.

'NA' means 'not available'.

While these are all Philips devices, all semiconductor manufacturers make zener diodes in one or more sizes. The data on Philips devices were used for this table because they were to hand and not because they are recommended above other makes. This table represents the extremes of size, power dissipation and voltage.

Table 24.3: Electrical and thermal characteristics of some zener diodes

There are reference diodes whose breakdown voltage is nearly independent of temperature, usually available in the 8-10 volt region, at a specified current. Below 5 to 6 volts the zener diode has a negative temperature coefficient and above, a positive one. **Table 24.3** gives some figures for typical zener diodes made by Philips.

The series resistor value ($R_{\rm s}$) is calculated so that the diode provides regulation when the input voltage ($V_{\rm s}$) is at its minimum when the load current ($I_{\rm L}$) is a maximum. It is important to check that the diode's maximum dissipation is not exceeded when these conditions are reversed, ie when $V_{\rm s}$ is at its maximum and $I_{\rm L}$ a minimum. The expression for the series resistor is:

$$R_{s} = \frac{V_{s(min)} - V_{zener}}{I_{L(max)} + I_{zener(min)}}$$

The resistor must be rated for

Shunt regulators - integrated circuits

There are many voltage reference devices made for shunt regulator purposes, ranging from 1.22 up to about 36V. Some have three terminals to allow fine adjustment. They are used in the same way as the zener diodes previously described

Shunt regulators - high voltage

Beam tetrodes used for linear power amplifiers need a screen supply, and the 4CX250 series in particular can sink or source screen current. A series string of zener diodes could be used to cope with this, but would use expensive high wattage diodes. The circuit of **Fig 24.19** transfers the problem to a cheaper







Fig 24.20: A series transistor regulator

power transistor, but does not remove the need for a series string of diodes. These can now be of low wattage and so cheaper. The higher the $h_{\rm FE}$ of the transistor or Darlington pair, the cheaper will be the diodes. Formerly gas filled voltage regulators were used, and are still available. As long as you allow for the difference between the striking and running voltages, the procedure is the same as that for zener diodes.

Series regulators

In these an active device is placed in series with the supply, and negative feedback applied in such a way that the output voltage remains constant in spite of varying load and input voltage. The output voltage, or a definite fraction of it, is compared with a reference voltage and the difference amplified to control the series pass element in such a way as to minimise the difference. The greater the gain of the amplifier, the better will be the final result, provided the circuit is stable. A single transistor may be good enough in less demanding situations.

The pass element can be either a bipolar or field effect transistor. Protection from failure of the pass transistor is advised to avoid damage from over-voltage (see below).

Figs 24.20 and 24.21 show the simplest type of regulator using only two semiconductors. As previously said, they are only suitable in less demanding situations. There is not much excuse for building voltage regulators out of discrete components, as integrated circuits are cheap and often better.

IC voltage regulators

There are many IC voltage regulators, of which only linear types will be considered here. They all have the elements so far



Fig 24.21: A series regulator using two compounded transistors as the series element



Fig 24.22: A 12V 500mA power unit using a regulator type LM7812CT



Fig 24.23: Adjustable voltage regulator using an IC. The value of RV1 is (V_{out} - 1.25)R1/1.25 ohms

described incorporated into a single chip, and often include various over-load and over-temperature protection. There are four main types:

- 1 Positive fixed voltage eg 5, 12, 15 and 24 V
- 2 Positive adjustable voltage, adjustable by external resistors
- 3 Negative fixed voltage
- 4 Negative adjustable voltage, adjustable by external resistors

All need capacitors connected close to their input and output pins to prevent oscillation, see **Fig 24.22**, and it is advisable to fit diodes to prevent capacitors in the load from discharging back through the IC.

This is particularly important for LM317 and LM1084 type adjustable types (**Fig 24.23**) - take the maker's advice! There is no excuse for attempting to add components to a fixed regulator to get an increased voltage; the adjustable ones cost little more.

Table 24.4 gives some typical examples. The circuits for adjustable types do vary from manufacturer to manufacturer (Fig 24.23 again).

Most IC voltage regulators have internal current limiting and some have 'fold back' current limiting in which the voltage falls sharply if you attempt to exceed the current limit, see **Fig 24.24**.

The input voltage must exceed the output voltage by a stated amount; this is called the drop-out voltage.

An external pass transistor, connected as shown in **Fig 24.25** for a positive regulator, may increase the output current. The resistor is chosen so that the transistor is turned on (by 0.6V on its base) when just before the IC's current maximum is reached. This applies particularly to the 723 type of IC where its ability can be extended almost indefinitely (note that the correct compensation capacitor must be connected according to the data sheet) [1]



* Low 'drop-out' type, ie it has a low voltage drop across the series transistor. More of these are now available.

Notes. There are many other different voltage and current rated stabilisers and they are made by many different manufacturers. All the high-powered devices must be fixed to a suitable heatsink. All 'fixed voltage' devices can have their voltage adjusted upwards by adding a resistor, a diode or a zener diode in series with their 'common' lead. The value of resistor varies with the device and the manufacturer, and the latter's literature should be consulted.

Table 24.4: IC voltage regulators



Fig 24.24: Voltage current characteristic showing 'fold-back'



Fig 24.25: Connecting an external pass transistor to increase the output current

The Radio Communication Handbook

Field effect transistors (FETs)

Instead of using bipolar transistors for the pass element, a MOS-FET (see the chapter on semiconductors) can be used with advantage. They are now cheap, and have the advantages that they are not subject to thermal run-away, have a reasonably constant gain with drain current, and a very low on-resistance. A disadvantage is that as they are only made in enhancement versions, the gate requires a voltage somewhere between 2 and 8V (according to type) above the source. For efficiency this should be derived from a low power auxiliary rectifier and transformer or winding. As MOSFETs have an integral reverse diode, protection from damage due to charge stored in capacitors after the regulator is not required.

Over-voltage protection

If the pass transistor fails to a short circuit condition, the whole input voltage (perhaps 18-20V for a 13.8V supply) will reach the output. Many rigs do not like this very much, and to avoid expense, some form of over-voltage protection ought to be included. The most common is called a crow-bar, so called because it short circuits the supply and either blows a fuse or operates a relay to open circuit the rectifier (see Fig 24.10(c)).



Fig 24.26: The TV de-gaussing thermistor used in Fig 24.10(c)



24.27: Current limiting and protection [Practical Wireless]



Fig 24.28: Principle of the constant-current circuit. TR1 small JFET; R to set current - depends on G_m of FET The type of thermistor used here comes from the de-gaussing circuit of a TV set, and is shown in **Fig 24.26**.

Over-current Protection

Most ICs have internal current limiting, but where augmentation of the ICs current is used, often with the 723, the internal limit may not work or may need too many millivolts in a current sensing resistor. The Maxim MAX 4373 is a very useful IC that needs very few millivolts from the current sensing resistor, and provides a latched over- current flag. **Fig 24.27** shows it being used to sense the voltage across an ammeter, and shut down a 723 IC by crowbarring an internal amplifier transistor. If you use this circuit, you must put a 1k resistor between pin 1 (Current Sense) of the 723 IC and ground, to prevent destruction of the transistor by excess current. You restore the latch by grounding pin 5 of the MAX 4373. Full details of the Max 4373 series are available from Maxim.

Constant Current Circuits

From time to time, a constant current source is needed, for example to charge a secondary battery (see below). A depletion mode FET with a source bias resistor will do the trick (see **Fig 24.28**), but the I_{DSS} of a junction transistor is only loosely specified. Corresponding to drop out voltage, the knee voltage of the FET has to be overcome before constant current is achieved. To save trouble, FETs with built in source resistors can be bought.

A similar arrangement with a bipolar transistor, whose base is held at a fixed potential, can provide a constant current up to several amps if required.

The LM317 adjustable regulator can be used in the circuit of **Fig 24.29**. The LM317 passes enough current to maintain 1.25V between the output and Adj pins, so the current in amps will be 1.25/R where R is in Ohms. As the circuit only has two connections, it can be used for either positive or negative supply, having due regard to polarity.

For a really high current supply, put a suitable choke in series with the primary of the transformer of a normal full wave circuit. Achieving the correct choke is easier done by trial and error!

SWITCH MODE POWER SUPPLIES

All the previously mentioned DC supplies transformed the mains, rectified it and perhaps regulated it. At 50Hz, the transformer is bulky and heavy. If a higher frequency could be used, the transformer and smoothing arrangements could be made much smaller. The switch mode device does just this, and was used in the thirties as a means of effectively transforming DC. With the advent of transistors, much higher frequencies, up to the MHz region could be used, also making efficient regulation possible, if needed.

The subject would fill a book not much smaller than this, so you should either buy a cheap switch mode power unit, or read a suitable maker's application note covering your need. In either case you



Fig 24.29: LM317 used as a constantcurrent regulator $I_{LOAD} = 1.25/R$

Туре	Voltage (V)	Weight (g)	Maximum size (mm)	Current range (mA)
AAA	1.5	9	45 10.5	0-25
AA	1.5	18	50.5 14.5	0-40
С	1.5	48	50 26.2	20-60
D	1.5	110	61.5 34.2	25-100
PP3	9	38	48.5 17.5 26.5	1-10
PP9	9	410	81 52 66	5-50
C (HP)	1.5	as 'C' above	e	0-1000
D (HP)	1.5	as 'D' above	9	0-2000

Note. Where there are two dimensions, the first is the length and the second the diameter. The current range is that which gives a reasonable life. Manufacturers do not often give capacities in ampere-hours. The shelf life of either type of cell is about a year although it can be improved by keeping it cold. 'HP' is the high-powered type.

Table 24.5: Characteristics of typical zinc-carbon cells and batteries

have to consider the EMC problem, for SMPSs are notorious for the interference they can create.

BATTERIES

The basic types of batteries have been described in the chapter on Principles.

There are two types, primary or one shot, and secondary or rechargeable. Strictly speaking, a 'battery' is an assembly of two or more 'cells', but a single cell is commonly also called a battery.

Primary Batteries

At present there are two main varieties, that are suitable for amateur use, based on zinc or lithium. The battery derives its energy from the metal used as the negative electrode. The positive electrode has an effect as well and has to be able to dispose of the hydrogen, which would otherwise be liberated there. A depolariser surrounds the electrode if it is unable to do this. For watches and similar purposes zinc-mercury oxide and zincsilver oxide cells are available at some cost.

Zinc-carbon

These form the oldest and cheapest primary cells and are called dry cells as the electrolyte, although not dry, is immobilised so that it cannot spill.

Three different electrolytes are used, an aqueous solution of ammonium chloride (sal ammoniac) in the cheapest, zinc chloride in 'high power' cells, and sodium hydroxide (caustic soda) in manganese-alkaline cells. **Table 24.5** gives some parameters of typical types.

Manganese-alkaline cells are made in the same sizes and Table 24.6 gives details.

	Туре	Voltage	Weight (g)	Capacity (Ah)
	AAA	1.5	11	1.2
	AA	1.5	22	2.7
	С	1.5	67	7.8
	D	1.5	141	18.4
	PP3	9	45	0.55
Note. The dimensions are as above and the capacity is in ampere- hours. They have a shelf life of several years.				

 Table 24.6: Characteristics of typical manganese-alkaline batteries

Zinc-air

These are similar to zinc-carbon, but use the oxygen of the air as the depolariser. You buy them sealed and they only 'come to life' when the seal is removed. Potassium hydroxide (caustic potash) is used as the electrolyte, and slowly absorbs carbon dioxide from the air, ending the life of the cell. They must be used in a well-ventilated housing. They have a higher energy density than zinc-carbon cells ie they pack more energy into a given weight or space.

Lithium

The negative electrode is the highly reactive metal lithium, so the electrolyte contains no water. The positive electrode is either iron disulphide (1.5V) or manganese dioxide (3V on load). The electrolyte is either an organic liquid or thionyl chloride (2.9V).

These cells have a long shelf life making them good for battery back up, and have a low internal resistance. They also present a fire hazard if broken or an attempt to charge is made.

Secondary Batteries

Lead-acid, Nickel-Cadmium (Ni-Cad), Nickel-Metal Hydride (Ni-MH) and Lithium are the only types in amateur use which will be described.

Lead-acid

This the earliest cell, with lead plates and dilute sulphuric acid electrolyte. Vehicle batteries nearly always use these, as the alternatives (Ni-Cad or Ni-MH, see below) are too expensive. They are heavy, but have very low resistance. One feature is that if left discharged for some time, the plates sulphate irreversibly and the battery is almost always ruined. The usual charging is at a constant voltage of 13.8V, with some form of current limiting to prevent too large a current flowing initially. Do not try to charge a 12V battery from a 13.8V PSU. If the mains fails or is disconnected, the battery will discharge into the PSU, possibly damaging it. Any charger should therefore contain a diode to prevent reverse current flow. Over-charging a sealed battery will result in explosive gases being generated and may burst the vent.

Nickel-Cadmium

Ni-Cads (1.2V) have an electrolyte of potassium hydroxide in water, which is attacked by carbon dioxide in the air. Today the cells are sealed to prevent this, and as such are much used by amateurs. **Table 24.7** gives data on a selection. Cadmium compounds are toxic and Ni-Cads should be disposed of with care; many local authorities make provision for this and should be consulted.

Charging can be done at a constant current of C/10 amps where C is the capacity in ampere-hours. This will be complete in about 14 hours (allowing for inefficiency) and moderate overcharging at this rate does not result in harm. This long charging time is a nuisance, so fast charge circuits have been developed. When fully charged, the Ni-Cad cell voltage actually decreases

Siz	e \	/oltage (V)	Capacity (Ah)	Weight (g)	
AA	A 1	L.2	0.18	10	
AA	1	L.2	0.5	22	
С	1	L.2	2.2	70	
D	1	L.2	4.0	135	
PP	3 8	3.4	0.11	46	
PP	9 8	3.4	1.2	377	
Note. The dimensions are the same as those for the zinc-carbon cells/batteries above.					

Table 24.7:	Characteristics	of	typical	nicad	(NiCd)	cells	and
batteries							



Fig 24.30: The Maxim MAX 712/713 Ni-Cad and Ni-MH fast charger ICs

with time. Maxim make a charger IC for Ni-Cads, the MAX 713. This detects the decrease and stops fast charge, **Fig 24.30**.

There is a memory effect with Ni-Cads if re-charged before being completely discharged; the cell 'remembers' that it was not fully discharged and will not be able to discharge fully after subsequent charge. Some authorities dispute this, believing that it only occurs after repeated discharge to less than complete. If your cell suffers from this, short out the cell only when discharged as much as it will. Beware of reversing the current through the cells of a battery; this damages them. Connecting a resistor across each cell of a battery is recommended, but not usually possible.

Opinion also differs with the procedure for storing cells that are not required. Unlike the lead-acid cell, Ni-Cads may be left discharged, and some have found this better than leaving them fully charged. Maker's advice is not readily available.

Nickel-metal hydride cells

They have advantages over nicads in that they have a higher energy density and they do not contain cadmium. A simple comparison between one of these and the same size in nicad is given in **Table 24.8**.

	Metal-hydride	Nicad
Capacity (Ah)	3.5	2.0
Voltage (V)	1.2	1.2
'Memory'*	None	Severe
Toxics	None	Cadmium
Discharge rate (A)	<12-15	<15
Overcharge capability	Cont. at C/5	Cont. at C/5

* 'Memory' is an alleged effect [3] which shows up if a cell is only partially discharged before recharging. It is said to reduce the capacity of the cell. This has been disputed [4].

Table 24.8: Comparison of metal hydride and nicad 'C' size cells [2]

Nickel-Metal Hydride

Ni-MH cells are very similar to Ni-Cads, the voltage is the same, but capacity for the same size is higher. There is no memory effect, but the self-discharge rate is higher. Ni-MH cells do not exhibit the decrease of voltage with time at full charge (like the Ni-Cads do); the voltage remains constant. The MAX 712 (Fig 24.30) detects this and stops fast charge.

Lithium-ion

Note that these are not lithium-iron! The negative electrode is carbon, and the positive lithium-cobalt oxide in most cells. The voltage starts at about 4V after charge and drops to 3V when discharged. Charging is best done at a constant voltage of 4.2V (4.1V if the positive electrode is lithium-nickel oxide). Analogue Devices market an ADP 3820 in versions suitable for charging both types (**Fig 24.31**).

Safety

As mentioned above, the electrolyte of lead-acid cells is sulphuric acid, and it should be treated with the greatest respect, and not allowed to touch the skin. If it does, it should be immediately washed off with running water. In particular the eyes should be protected from it. If it gets on clothes, if left, it will slowly make a hole. The explosive nature of the gas evolved by unsealed cells has already been noted. Sparks from the terminals on connection or disconnection can ignite the gas, and the entire cell could explode.

The electrolytes of the other types are undesirable also, and should be washed off if they contact the skin. Lithium is an extremely reactive metal, and if a cell containing it bursts, a fire may start. Do not attempt to destroy such a cell by burning.

REVERSE BATTERY PROTECTION

Applying power with the wrong polarity can damage equipment. Here are four simple ways to prevent this:

- 1 Put a power diode in series with the load. This has the disadvantage of wasting a volt or so across the diode, but a Schottky diode would be better (0.31V at 8A for the 95SQ015). See Fig 24.32(a).
- 2 Put a power diode in parallel with the load and a fuse in series. If the power is incorrectly applied, the diode conducts and the fuse will blow, see **Fig 24.32(b)**.
- 3 Use a relay to switch the power with a diode in series with the relay, which will then only operate if the power is correctly applied, **Fig 24.32(c)**.
- 4 Use a power MOSFET in the circuit reported by G4CLF. The MOSFET is only turned on by the correct power supply polarity. The 'on' resistance of available MOSFETs is so low that it may be neglected. See **Fig 24.32(d)**.



Fig 24.31: The Analog Devices Lithium-ion fast charger IC







Fig 24.34: A shunt regulator suitable for intermittent generators



Fig 24.32: Four methods of reverse-polarity protection. D1 is a silicon diode; in (a) it must carry the whole current. In (c), S is the on-off switch, A/1 is the relay operating coil and A1 is the normally open relay contact. (d) Using a p-channel MOSFET

RENEWABLE ENERGY SOURCES

Wind, Water and Pedal Generators

These may not find much application at home, but could be useful in portable operation. As all of them supply power intermittently, a rechargeable battery will be needed. This implies a regulator, and a simple shunt regulator is all that is necessary, plus a means of preventing reverse current. A wind generator is shown in **Fig 24.33**, and one type of regulator is shown in **Fig 24.34**.

Solar Cells

A photograph of a solar cell is shown in **Fig 24.35**; they come in various sizes. You cannot estimate the available power by exposing it to bright sunlight, then measuring the no-load voltage and the short circuit current. Thévenin's theorem does not



Fig 24.35: One type of solar cell

apply, but many makers will provide you with performance curves.

Thermocouples

In about 1820, Seebeck noticed that if one junction between two metals was heated, and the other cooled, an EMF was generated. Modern materials [5] make possible a power generator based on this effect, but the efficiency is not high. **Fig 24.36** shows one made to use the waste heat from a kerosene lamp to power a valve radio. 90V HT, 9V grid bias and 1.4V filament supply was available. Home construction might be attempted, but there may be a difficulty in getting the materials.

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